



Tagung der GI-Fachgruppe "Software-Messung und -Bewertung"

Fraunhofer IESE, Kaiserslautern, Germany

December 7, 2017

Continuously Monitoring Project Deadlines in Software Development

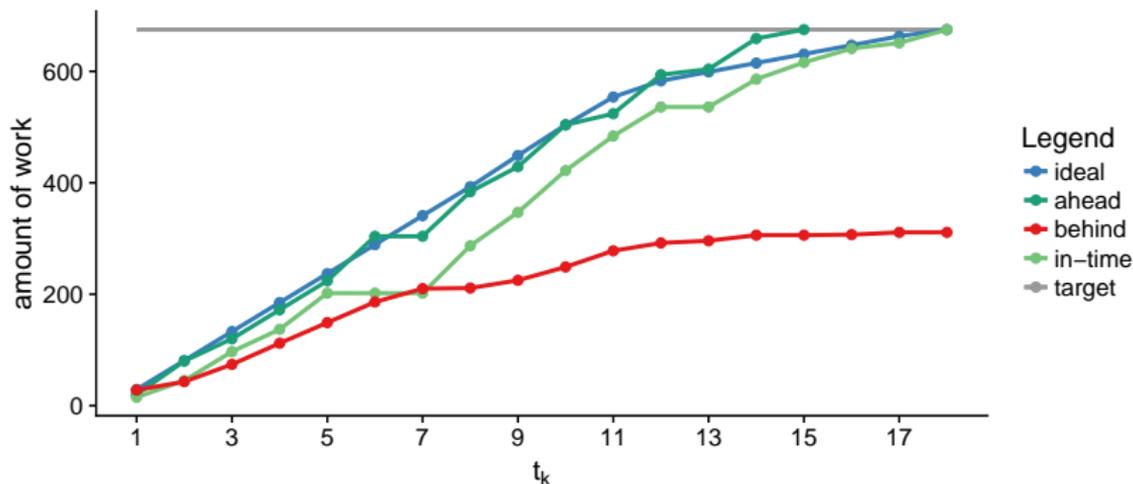
Thomas M. Fehlmann¹ **Eberhard Kranich²**

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Duisburg, Germany
eberhard.kranich@e-p-o.com



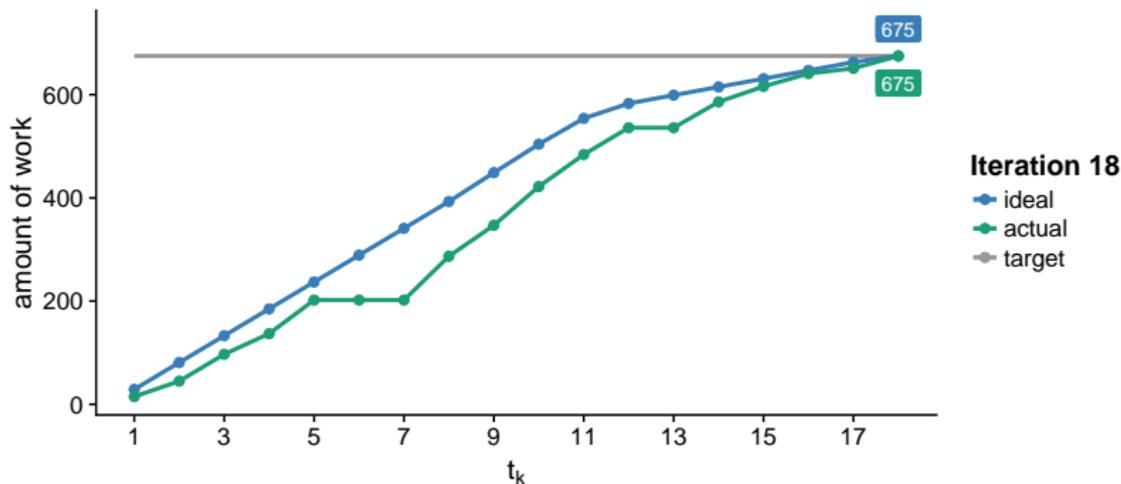
Burn-up Chart at Deadline



amount of work user story points, use case points, CFP, FP,
 # use cases, # test cases/steps, effort, etc.

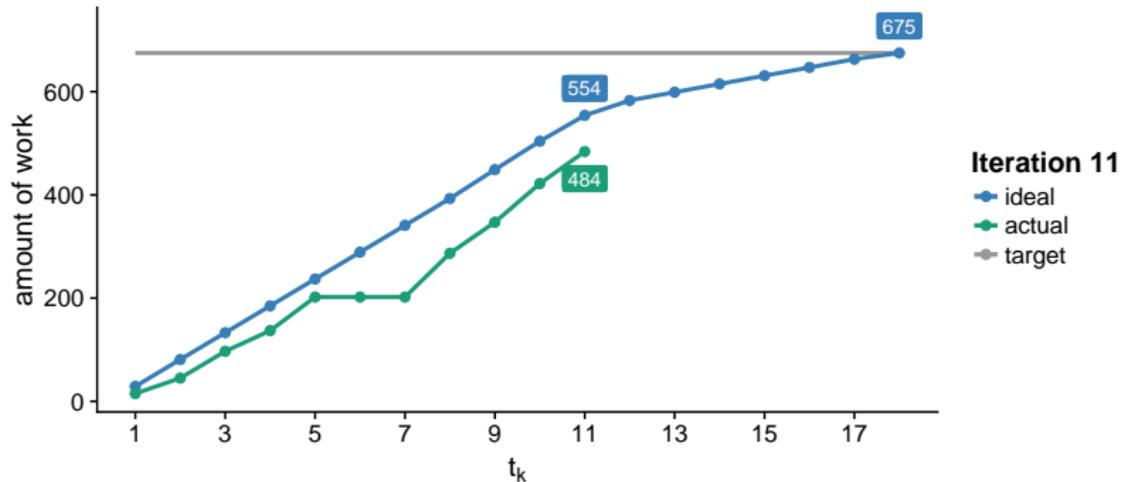
t_k point in time of measurement ($1 \leq k \leq n$)

Calculation Rule

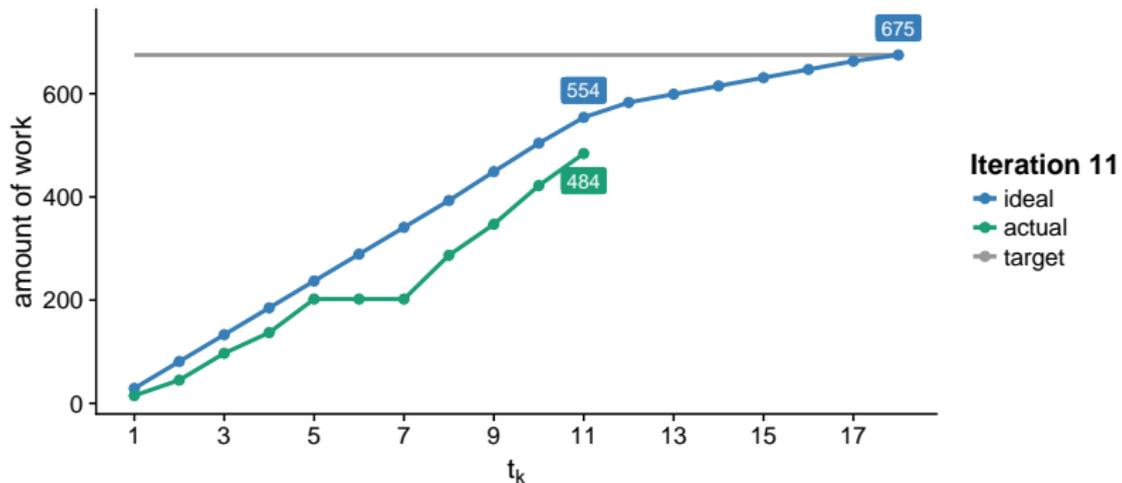


$$w_x(t_k) = \begin{cases} x(t_1), & \text{for } k = 1, \\ w_x(t_{k-1}) + x(t_k), & \text{otherwise.} \end{cases} \quad (x \in \{p, c\})$$

Typical Question



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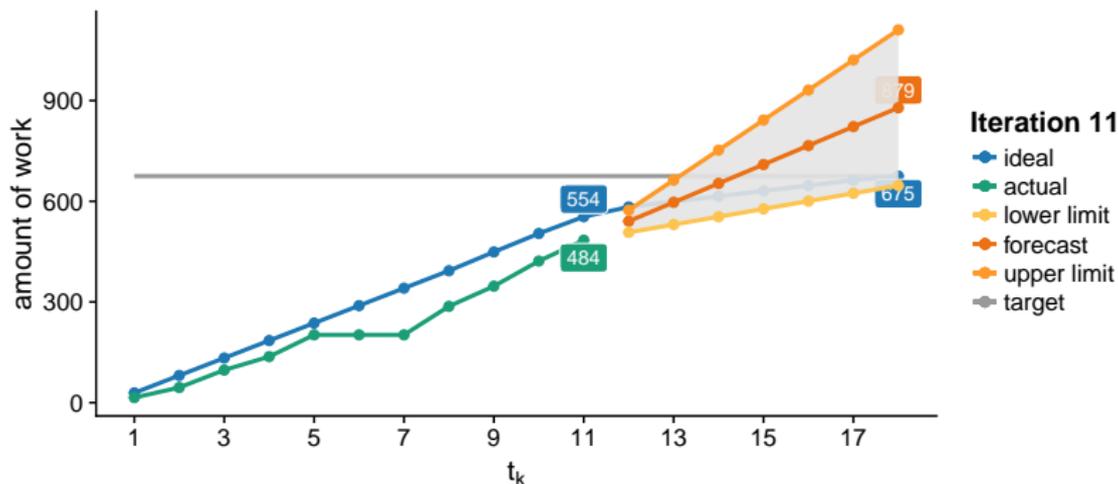


”Can we expect that all planned work will be completed at project deadline?”

Rule of Thumb Procedure

1. At actual iteration k , consider the work completed during the last k_0 iterations (incl. the actual iteration),
2. calculate the mean and standard deviation accordingly,
3. update the burn-up chart.

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Applying forecast Package

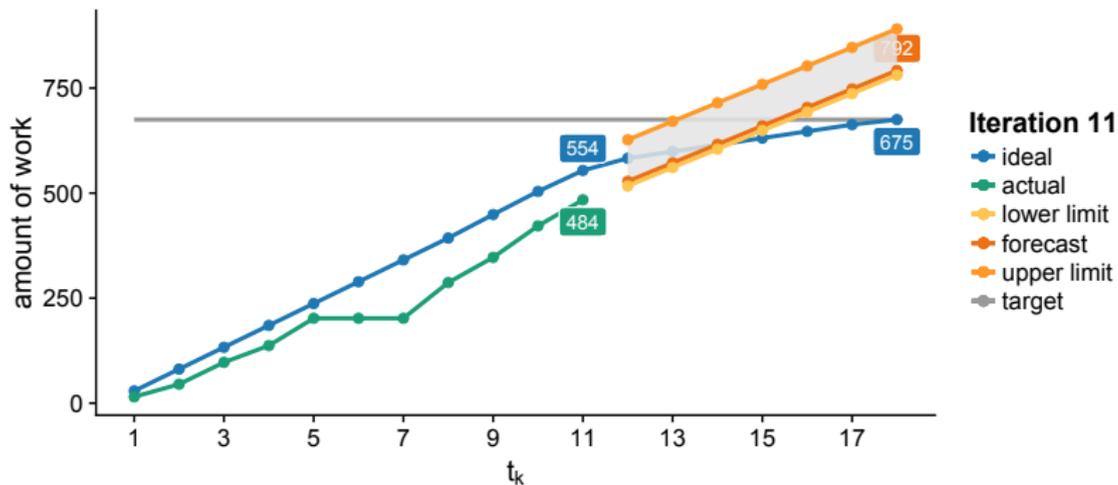
```
fc ← forecast(data=c[1:tk]), h=tn-tk, level=c(95))
```

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```
⇒ avg ≈ 44, Lo95 ≈ -11, Hi95 ≈ 99
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Applying forecast Package



`fc ← forecast(data=c[1:tk]), h=tn-tk, level=c(95))`

$\Rightarrow \text{avg} \approx 44, \text{Lo95} \approx -11, \text{Hi95} \approx 99$

Fundamental Property

Calculation Rule

$$w_x(t_k) = \begin{cases} x(t_1), & \text{for } k = 1, \\ w_x(t_{k-1}) + x(t_k), & \text{otherwise.} \end{cases}$$

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Mathematical Point of View

Burn-up charts depict order statistics!

Characteristics

The new approach

- ▶ utilizes order statistics and their properties,

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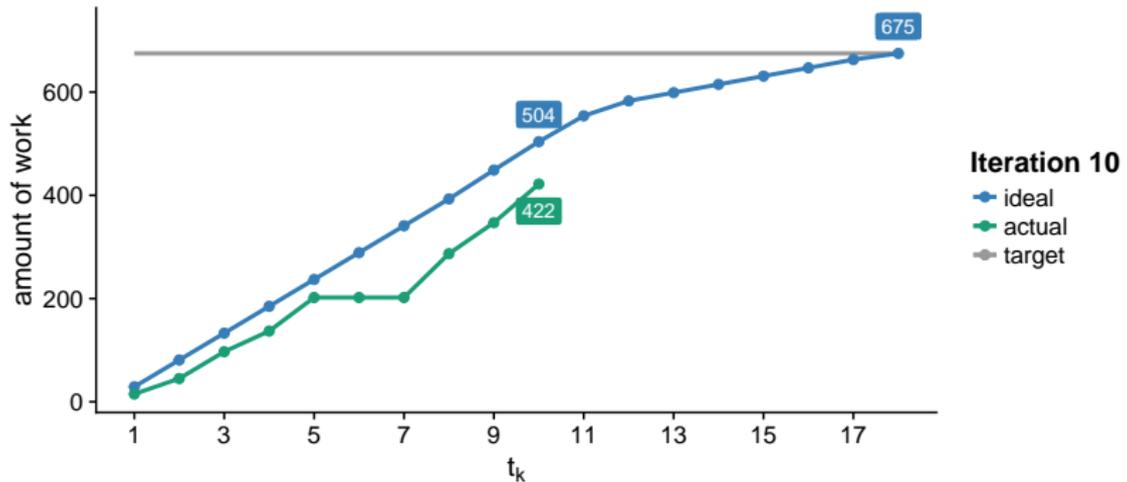
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- ▶ factors in the gap between planned and completed work,

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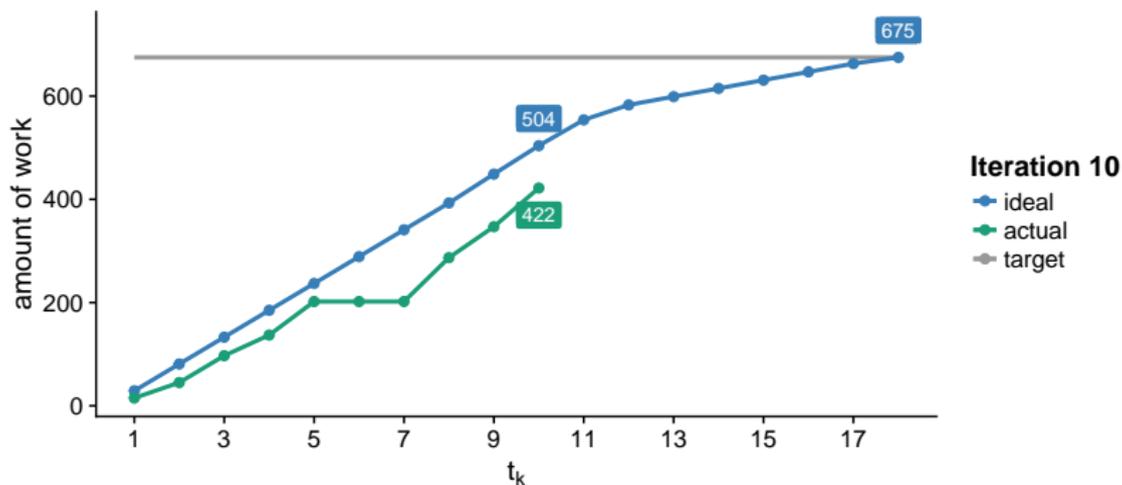
The new approach

- ▶ utilizes order statistics and their properties,
- ▶ factors in the gap between planned and completed work,
- ▶ provides deadline estimates based on serial number analysis.

Updating Rules at t_k

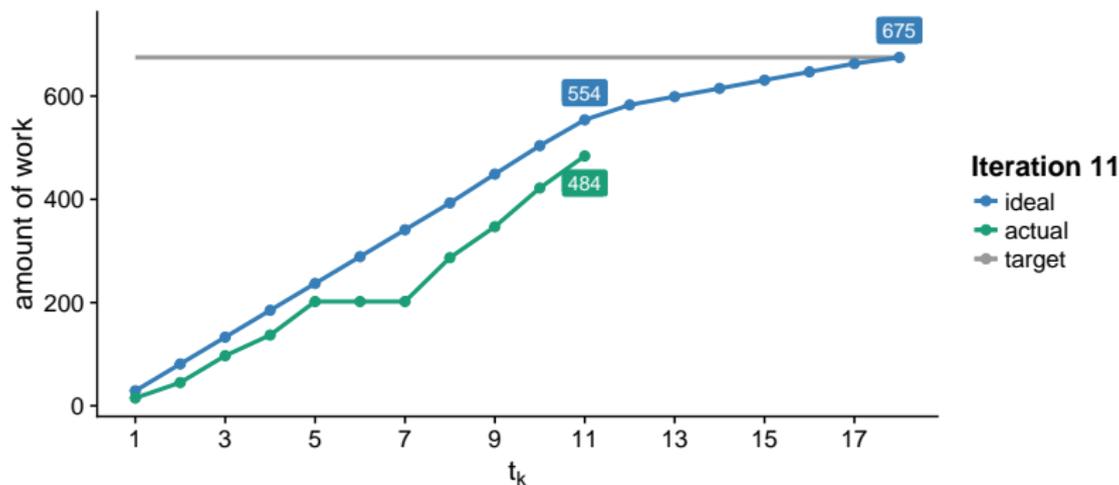


Updating Rules at t_k



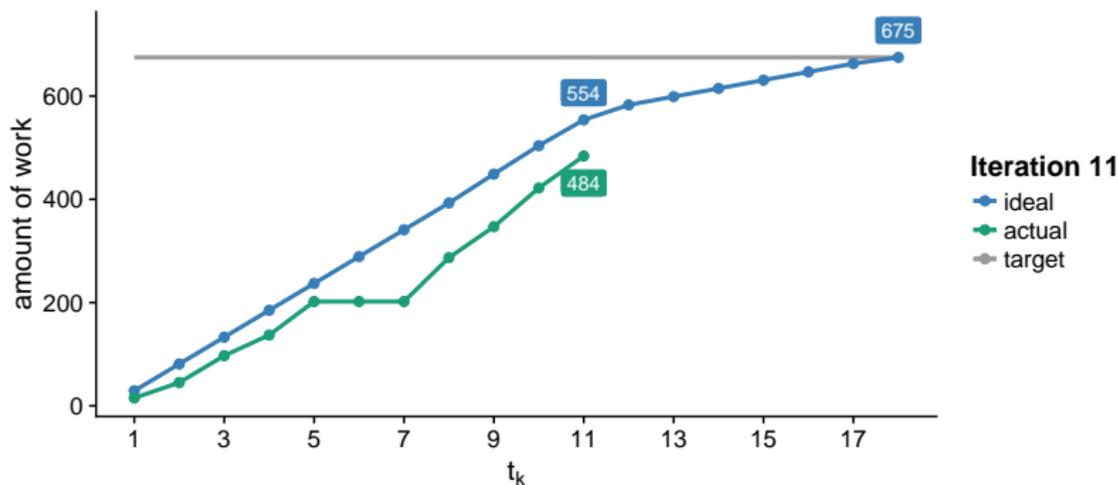
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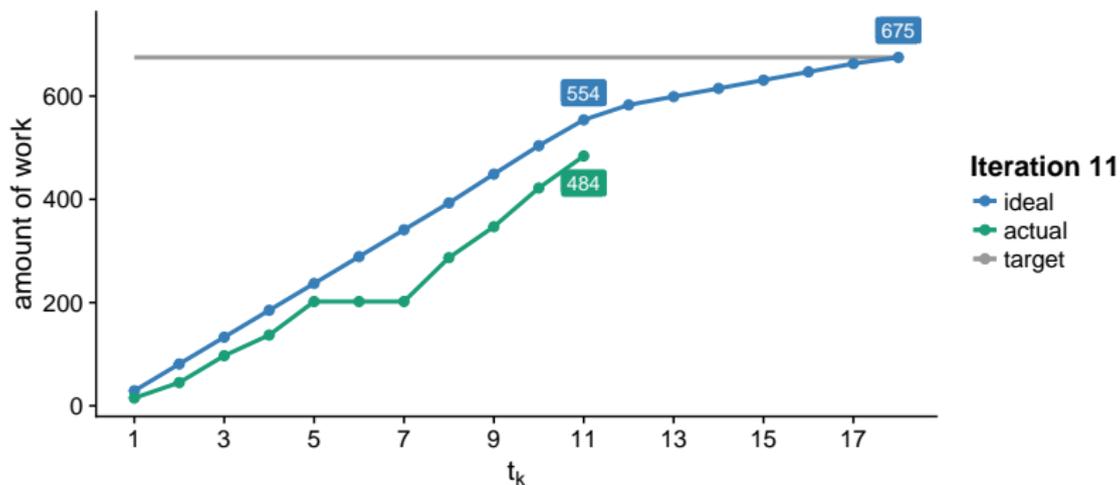
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$$w_c(t_k) \leftarrow w_c(t_{k-1}) + c(t_k), \quad (1)$$

$$\Delta_{t_k} \leftarrow c(t_k) - p(t_k), \quad (2)$$

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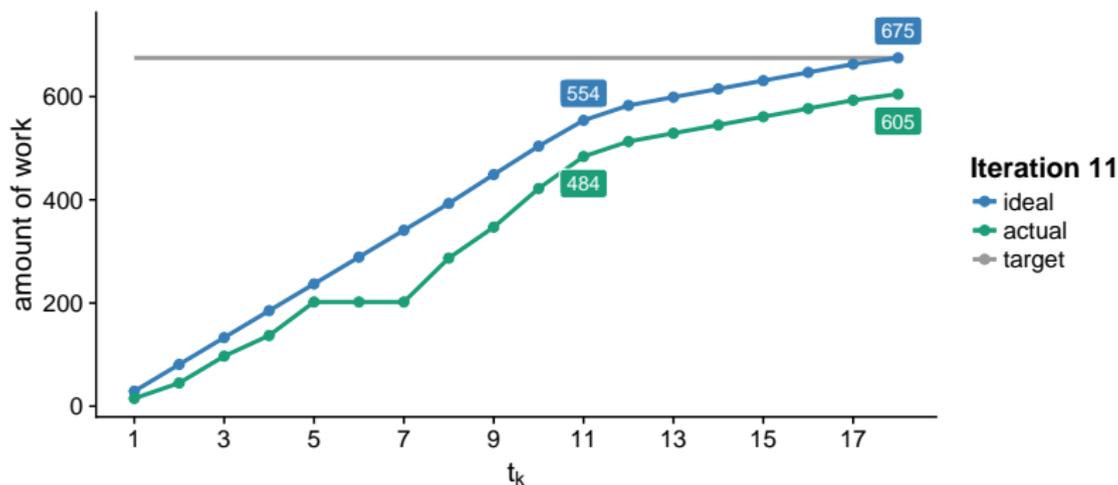


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Estimate the size N of a population marked with serial numbers after a single sample of n serial numbers (with $n < N$) has been observed.

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Examples

- ▶ German tank problem,
- ▶ Number of taxis in a city, of marathon runners in a race, etc.

Bayes' Estimates

$$\hat{w}_c(t_{n+i}) = \left\{ \right.$$

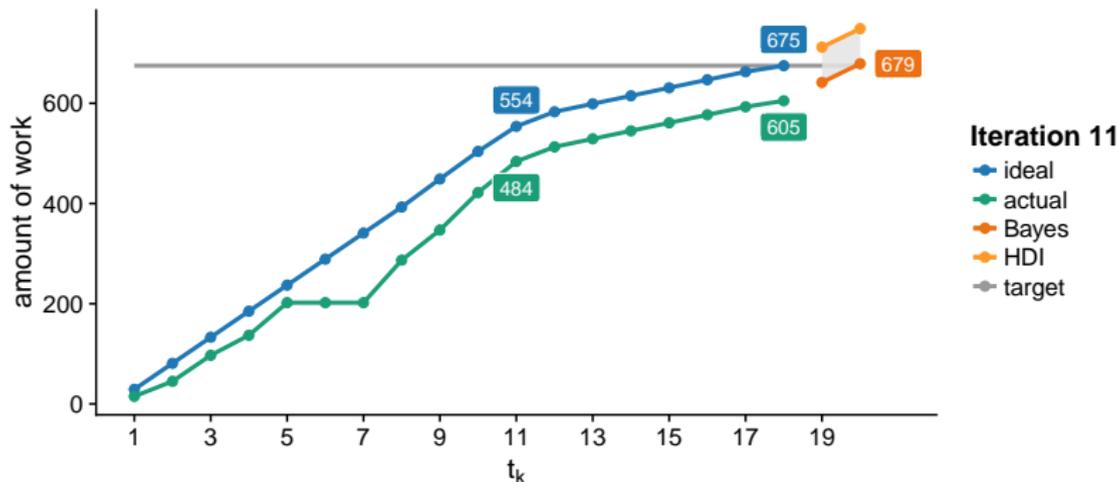
Bayes' Estimates

$$\hat{w}_c(t_{n+i}) = \begin{cases} \frac{t_{n-1}}{t_{n-2}} (w_c(t_n) - 1), & \text{for } i = 1, \end{cases}$$

Bayes' Estimates

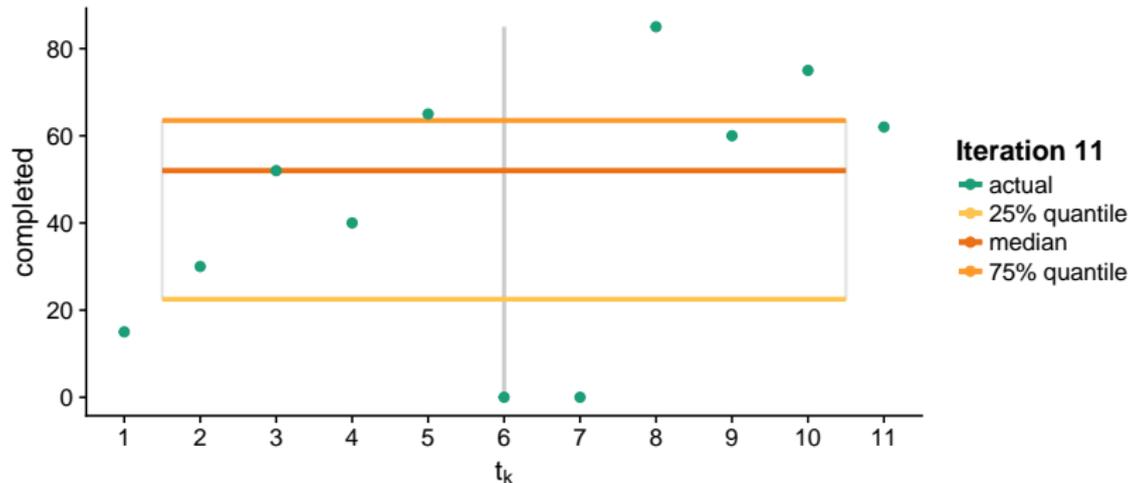
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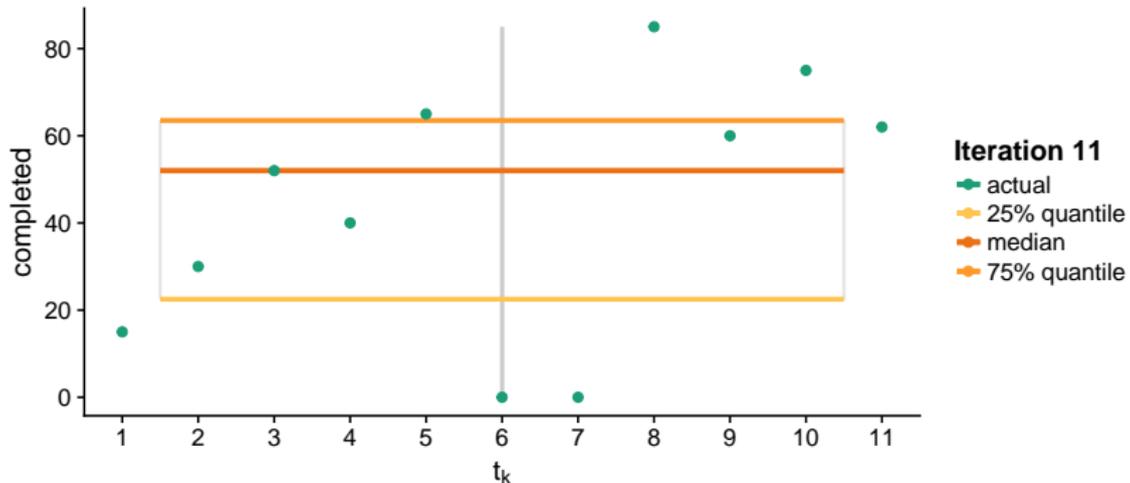
Five-Number Summary



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min	25%	median	75%	max
0.0	22.5	52.0	63.5	85.0

Five-Number Summary



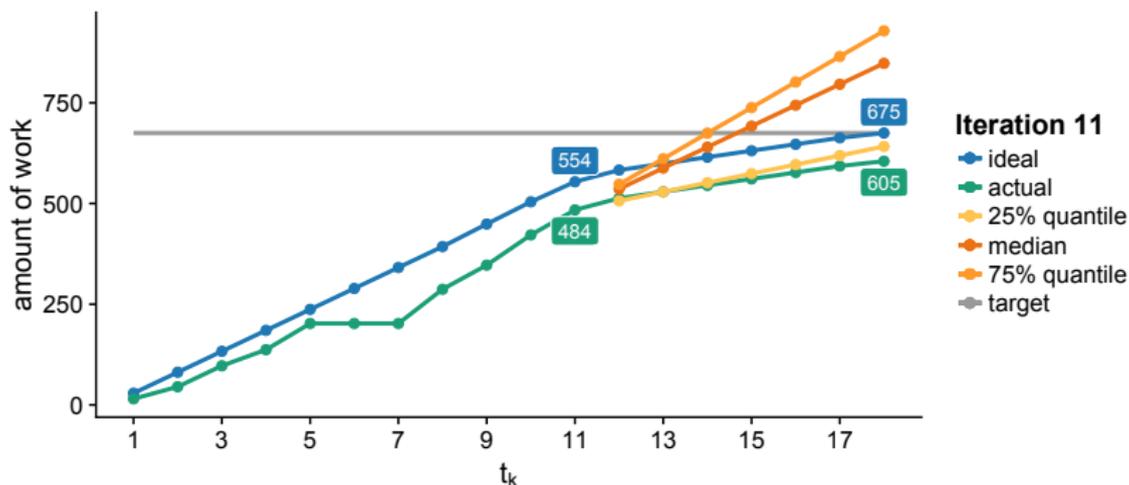
Five-Number Summary

i		1	2	3	
q_i	min	25%	median	75%	max
$c_{[q_i]}$	0.0	22.5	52.0	63.5	85.0

Quantile Graphs & Estimates

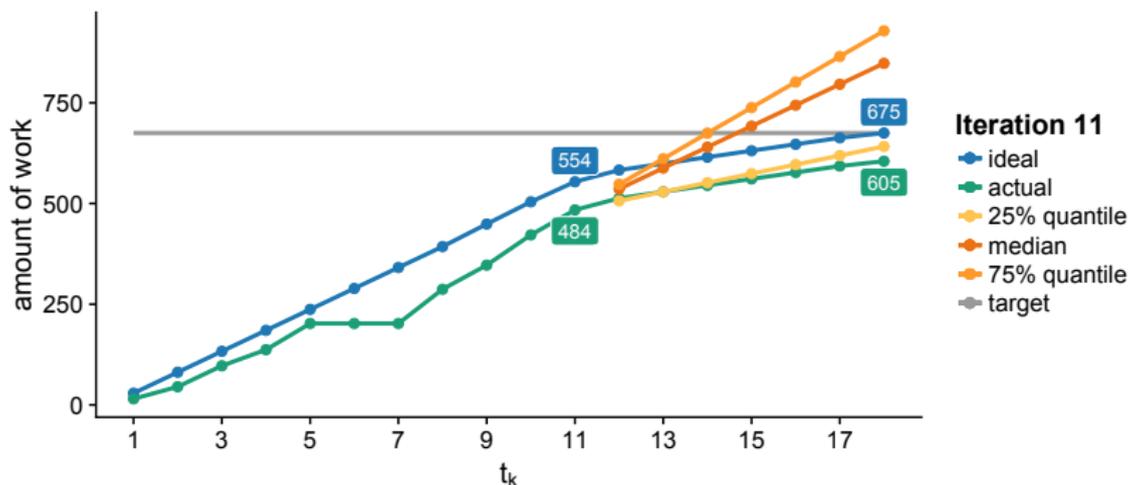
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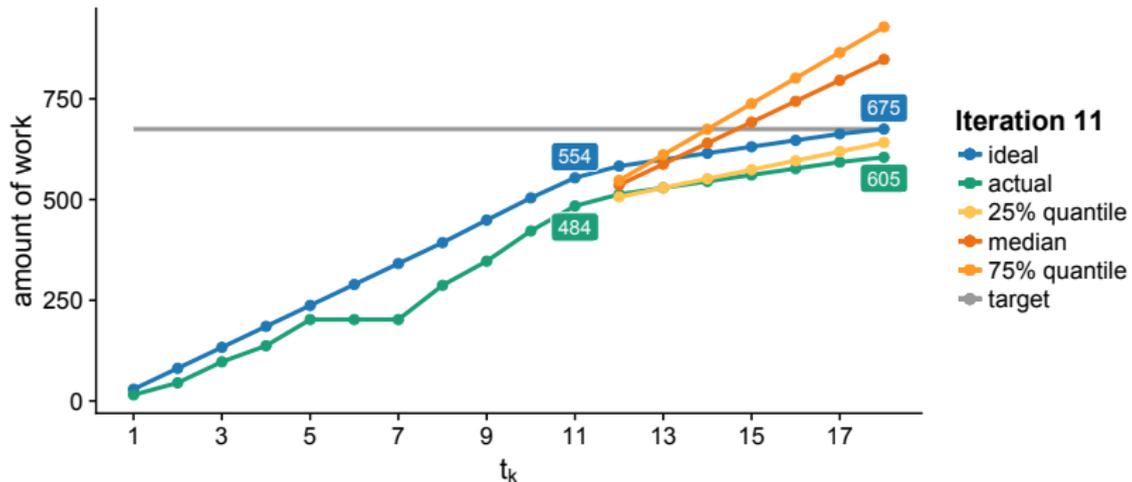
Quantile Graphs & Estimates



Quantile functions: $w_{c_{[q_i]}}(t_j) = w_c(t_k) + (t_j - t_k)c_{[q_i]}$,

Deadline estimates: $\hat{t}_{c_{[q_i]}} = t_k + \frac{1}{c_{[q_i]}}(w_p(t_n) - w_c(t_k))$.

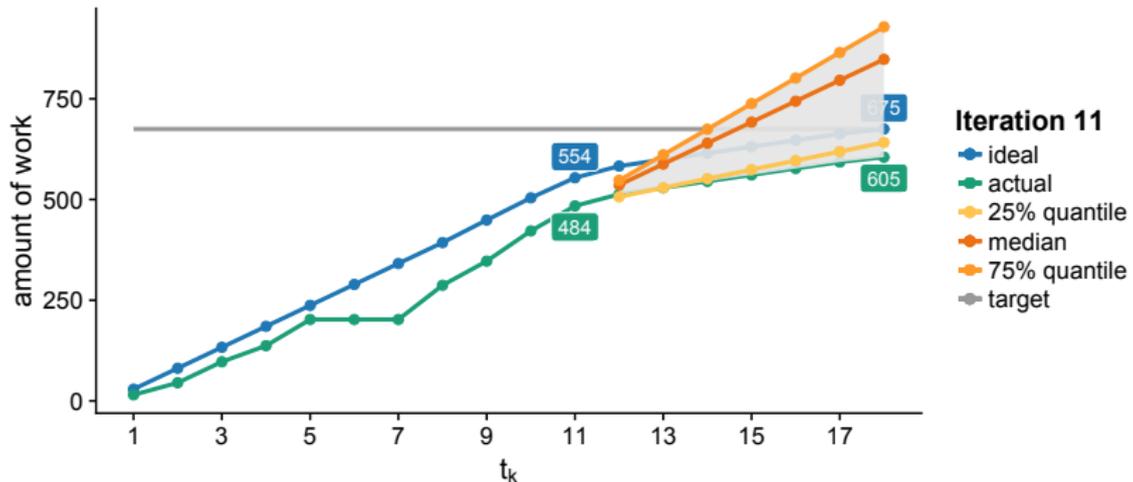
Stakeholder's Questions



Q1: "What amount of completed work can I expect at the specific point in time t_{k_0} ?"

Q2: "At which point in time can I expect that a certain amount of planned work is completed?"

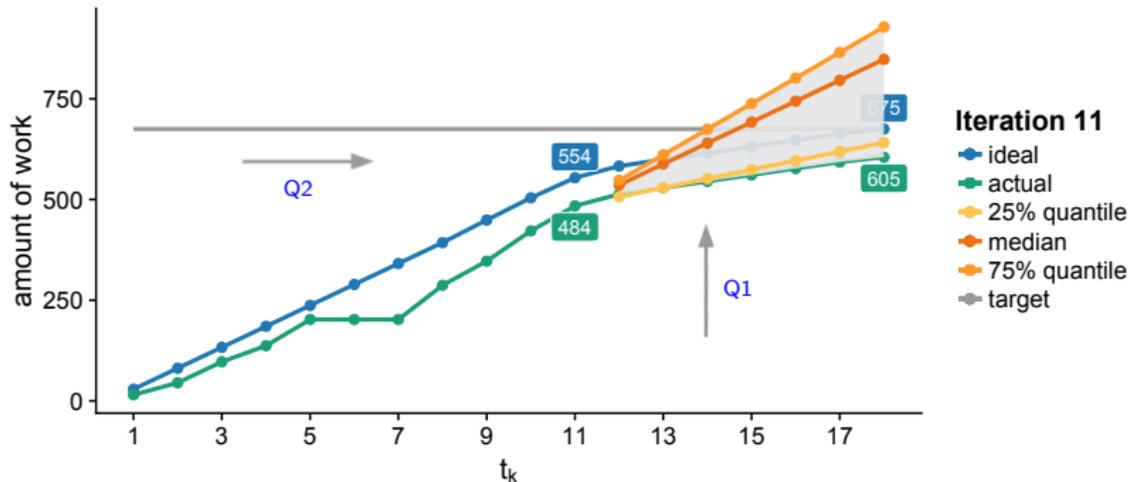
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Scope Creep Updating Rules

t_k	11	12	13	14	15	16	17	18
p		29	16	16	16	16	16	12
w_p	554	583	599	615	631	647	663	675
w_c	484	513	529	545	561	577	593	605

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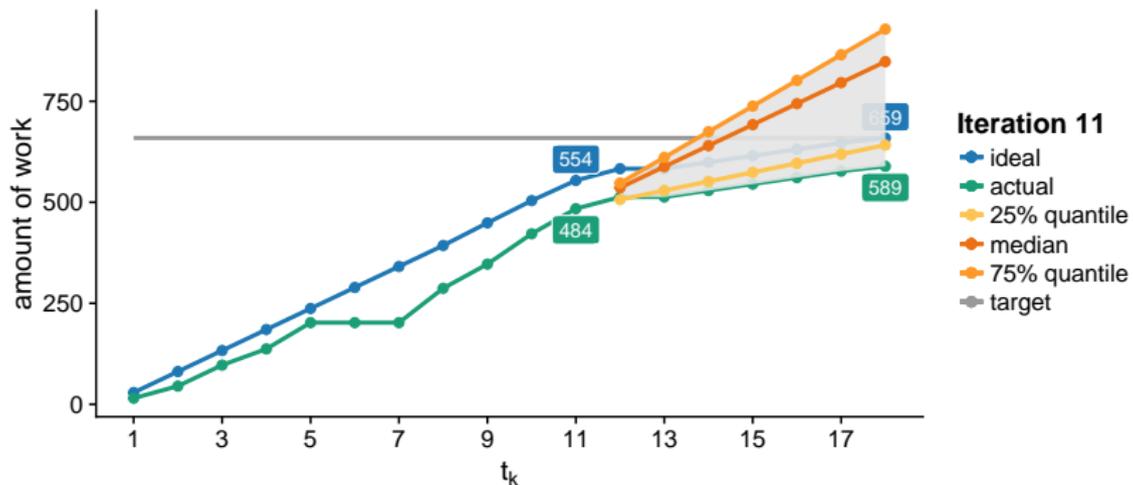
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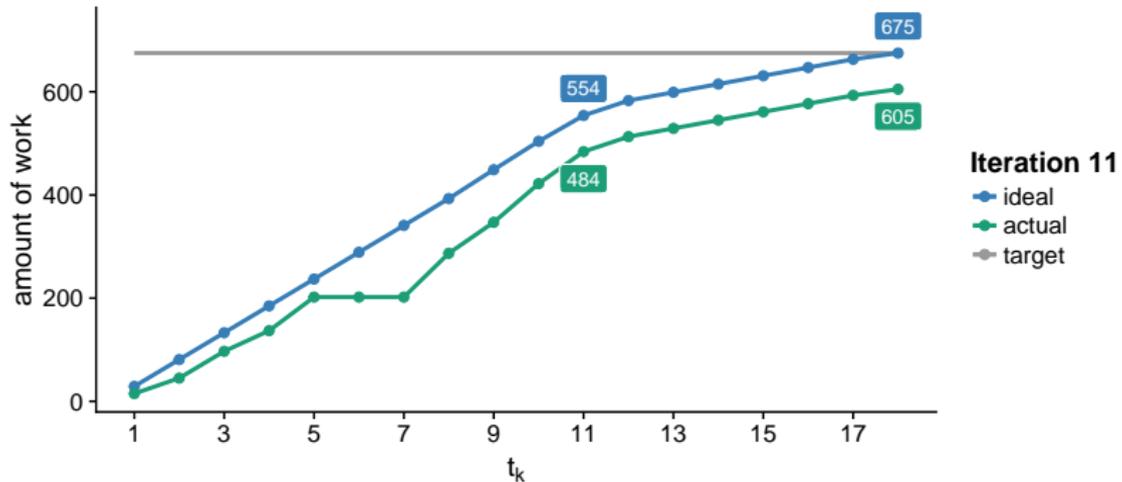


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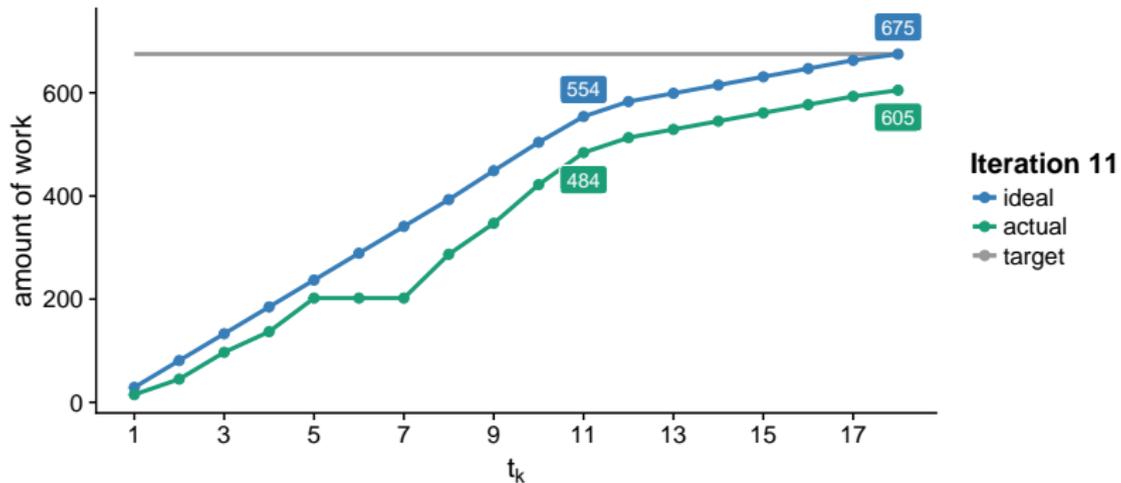
$$w_c(t_j) \leftarrow w_c(t_j) + sc.$$

Capable Progress Indicator



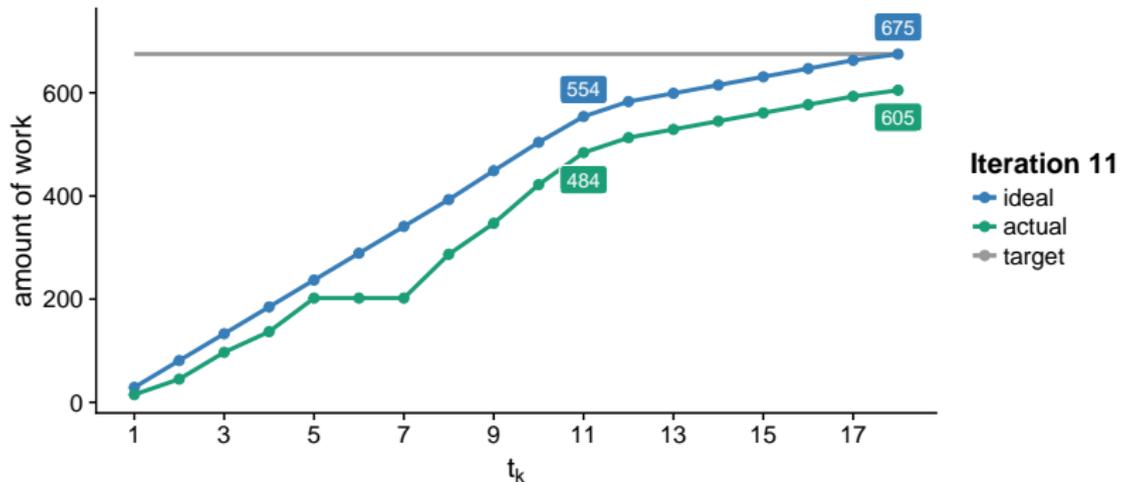
$$w_c(t_{k+j}) \leftarrow w_c(t_{k+j}) + \Delta t_k \quad (3)$$

Capable Progress Indicator



$$w_c(t_{k+j}) \leftarrow w_p(t_{k+j}) + \sum_{i=1}^k \Delta t_i \quad (3')$$

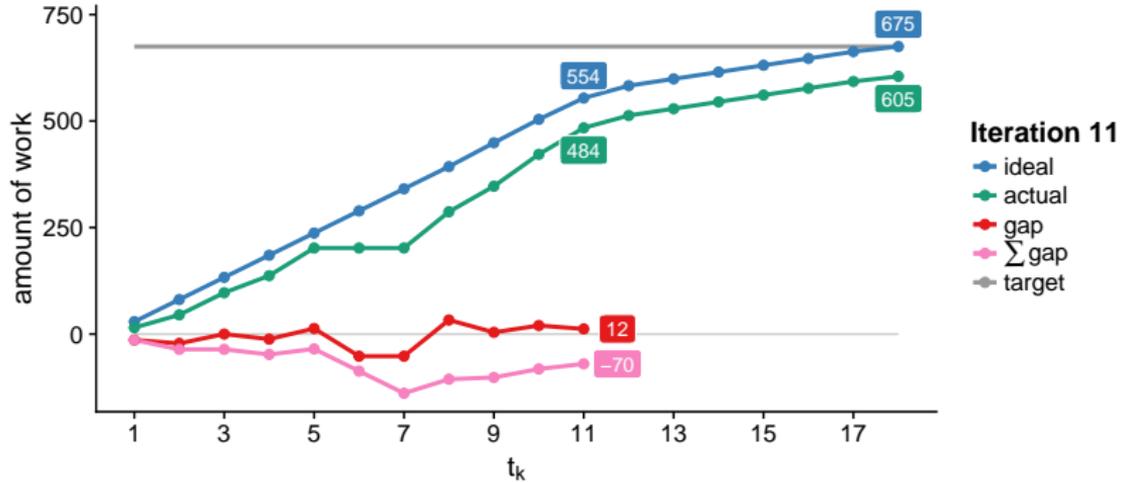
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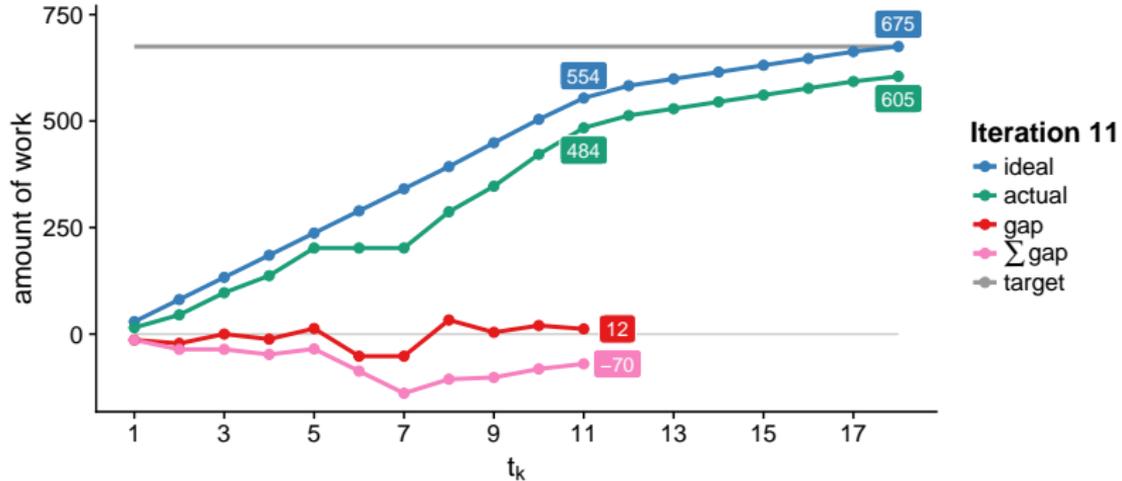
$$w_c(t_{k+j}) \leftarrow w_p(t_{k+j}) + \sum_{i=1}^k \Delta t_i \quad (3')$$

$\Rightarrow \sum \Delta t_i$ is a capable indicator for project progress

Monitoring Δt_k and $\sum \Delta t_i$

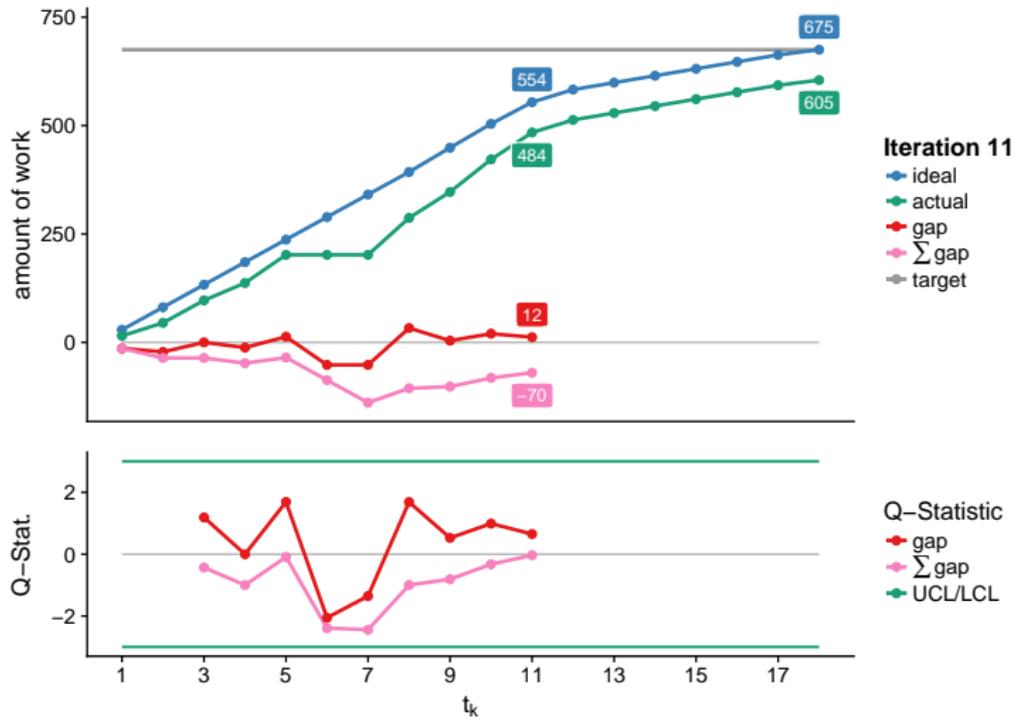


Monitoring Δt_k and $\sum \Delta t_i$



⚡ Δt_k and $\sum \Delta t_i$ have disjoint control limits! ⚡

Q Control Chart



Summary

The new approach

- ▶ utilizes order statistics and their properties,
- ▶ factors in the gap between planned and completed work,
- ▶ provides deadline estimates (Bayes and/or quantiles)
- ▶ enables to realize the direct consequences of scope creep,
- ▶ makes more information available by SPC Q control charts,
- ▶ is easy to implement.

Future Work

Next Steps

- ▶ Conducting extensive practical experiments,
- ▶ extending the approach by Bayesian data analysis,
- ▶ refining the SPC add-on to detect out-of-control conditions,
- ▶ etc.